

Linear programming

math121-1-linprog Introduction to linear programming

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Linear programming

Optimization projects are quite common, i.e. one needs to find a best numerical solution.

This is usually either a request for finding a maximum or a minimum and sometimes the function to be optimized is linear.

Sometimes one has bounds on the solutions and these are sometimes linear.

Example: Suppose we want to make animal feed as cheaply as possible. We have two feed mixed which we can use. Mix A, costs 10 kr/kg, but mix B costs 20 kr/kg.

The two mixes are different so the energy content of mix A has 500 Kcal but B has 4000 Kcal/kg. Mix A has a lot of protein, 200g per kg of mix, B has 100g per kg.

A farmer wants to combine the two feeds and minimize costs, but still fulfill the needs of the animals. They need at least 2000 Kcal/day and 400g of protein per day.

What is the optimal mix of the two feeds?

Linear objective function

Want to maximize a function of e.g. 2 variables:

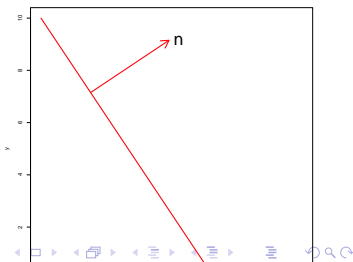
$$z = ax + by$$

but there may be many more variables.

The objective function is a constant, $z = z_0$, if $ax + by = z_0 \Rightarrow$ on a straight line.

The objective function increases in the direction of the normal vector, $\mathbf{n} = (a, b)'$.

Example: Suppose we want to produce two products, A and B where the profit is 3kr of each unit of product A but 2 kr per unit of product B. If we produce a total of x units of A and y units of B then the total profits are $3x+2y$.



The solution set

The set may be empty

The set may be unbounded

There may be a unique solution to the problem

The general form

In matrix and vector notation:

$$\min_x c'x$$

w.r.t.

$$Ax \leq b$$

Shadow values

At the optimum, the value of the objective functions (z^*) of a linear programming problem is attained with some constraints active, i.e. $\mathbf{a}'_i \mathbf{x}^* = b_i$, but others may not be, i.e. $\mathbf{a}'_i \mathbf{x}^* < b_i$. One can view the optimum value of the objective function as a function of these constraints $z^* = f(b_1, b_2, \dots)$.

When we relax the constraints, the solution can only improve.

The **shadow value** of a constraint is the answer to "how much does z^* increase if we relax $\mathbf{a}'_i \mathbf{x}^* \leq b_i$ by one unit".

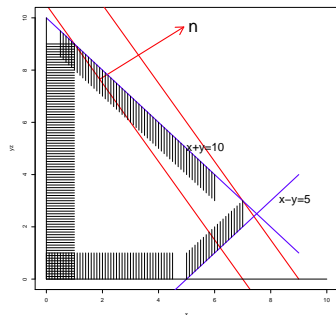
We can write this as $\frac{\partial z^*}{\partial b_i}$.

A visual solution

$$\min_x c'x$$

w.r.t.

$$Ax \leq b$$



GeoGebra is an excellent tool to draw the figures
<https://www.youtube.com/watch?v=qjDG940t-PA&feature=relmfu>

Example (from a 2004 exam in Iceland) Draw a figure and use it to find the values, x and y , which minimize $z = 2x - y$ with respect to

$$4x + 3y \leq 12$$

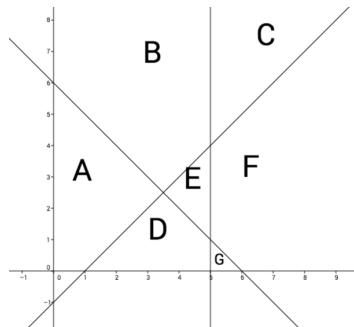
$$-x + y \leq 2$$

$$x + 2y \geq 2$$

$$x, y \geq 0$$

An example

$$\begin{array}{rcll}
 \max z = & 3x & - & 4y \\
 \text{w.r.t.} & x & - & y \leq 1 \\
 & x & & \leq 5 \\
 & x & + & y \leq 6 \\
 & x & & \geq 0 \\
 & y & & \geq 0
 \end{array}$$



Orðalisti

* Línuleg bestun

An example