Introduction to nonlinear statistical models stats545.5 545.5 Extending the linear model

Gunnar Stefansson

September 3, 2022

Gunnar Stefansson

Introduction to nonlinear statistical mode

September 3, 2022 1 / 4

The assumptions - and what goes wrong

$$\mathsf{y} \sim \mathsf{n}\left(\mathsf{X}\boldsymbol{\beta},\sigma^{2}\boldsymbol{I}\right)$$

may be wrong.

Simple variance exceptions are easy to handle:

- $Vy_i = u_i \sigma^2$ where u_i are known
- $\Sigma_v = \sigma^2 B$ where B is known
- $\Sigma_{\rm y}$ may contain "a few" unknown parameters

Maximum likelihood

The MLE is usually a good estimator Applies to very many estimation problems Need to specify the complete likelihood function Can take into account dependence, different variances, non-normality, nonlinear response etc Examples: Gamma mean, fish growth, length-weight relationships.

Nonlinear least squares

Common model:

$$Ey_i = g(x_i, \beta), \ 1 \le i \le n$$

Common estimation method:

$$min_{\beta}\sum_{i}(y_{i}=g(x_{i},\beta))^{2}$$

Also need to estimate uncertainty. Use Hessian or bootstrap.

- A - The sec

▲ 同 ▶ ● ● ▶

Copyright 2021, Gunnar Stefansson This work is licensed under the Creative Commons Attribution-ShareAlike License. To view a copy of this license, visit http://creativecommons.org/licenses/by-sa/1.0/ or send a letter to Creative Commons, 559 Nathan Abbott Way, Stanford, California 94305, USA.